



1. Consider the following neural network. Single-circled nodes denote variables (e.g.,  $x_1$  is an input variable,  $h_1$  is an intermediate variable,  $\hat{y}$  is an output variable), and double-circled nodes denote functions (e.g.,  $\Sigma$  takes the sum of its inputs, and  $\sigma$  denotes the logistic function  $\sigma(x) = \frac{1}{1+e^{-x}}$ ). In the network below,

$$h_1 = \frac{1}{1 + e^{-x_1 w_1 - x_2 w_2}}.$$

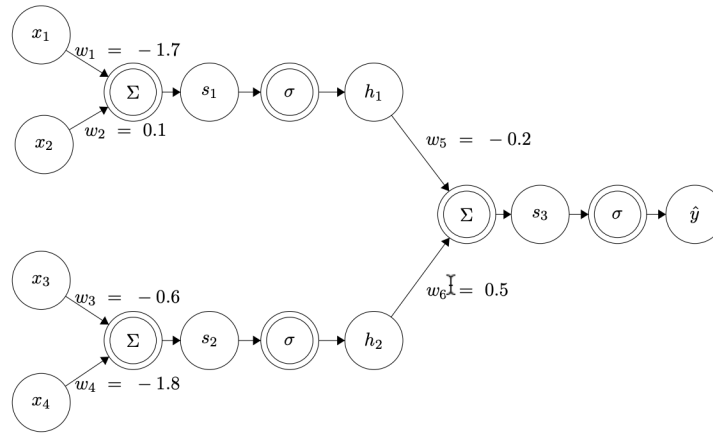


Figure 1: Neural Net architecture

Suppose we use an L2 loss function:

$$L(y, \hat{y}) = \|y - \hat{y}\|_2^2.$$

We are given a data point  $(x_1, x_2, x_3, x_4) = (-0.7, 1.2, 1.1, -2)$  with true label  $y = 0.5$ .

Use the backpropagation algorithm to compute the partial derivative:  $\frac{\partial L}{\partial w_1}$ .

2. The standard cost function for k-means clustering is defined as:

$$L = \sum_{j=1}^k \sum_{x_i \in S_j} \|x_i - \mu_j\|_2^2$$

where  $S_j$  is the set of data points  $x_i$  assigned to cluster  $j$ , and  $\mu_j$  is the centroid of cluster  $j$ .

Answer the following:

(a) **Optimality of the Centroid and Distance Metrics:**

- i. Prove that for a given set of points  $S_j$  assigned to a cluster  $j$ , the unique vector  $\mu_j$  that minimizes  $\sum_{x_i \in S_j} \|x_i - \mu_j\|_2^2$  is the sample mean of the points in  $S_j$ .
- ii. How would the optimal cluster center  $\mu_j$  change if the  $L_2$  norm (Euclidean distance squared) in the cost function were replaced with the  $L_1$  norm (Manhattan distance), i.e.,  $L' = \sum_{j=1}^k \sum_{x_i \in S_j} \|x_i - \mu_j\|_1$ ? Provide a characterization of this new optimal center (e.g., geometric median).

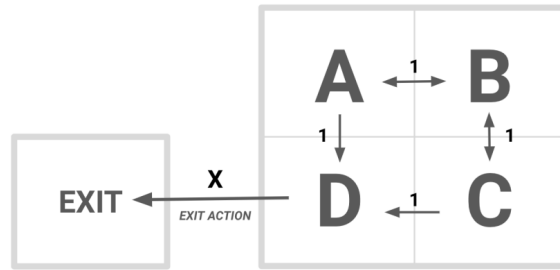
(b) **Convergence and Initialization:**

- i. The k-means objective function  $L$  is non-convex. Explain the implications of this non-convexity for the convergence of the algorithm. Why does the standard k-means algorithm (Lloyd's algorithm) guarantee convergence to a local minimum but not necessarily the global minimum?

(c) **Relationship to Gaussian Mixture Models (GMMs):**

- i. What specific assumptions must be made about the covariance matrices and mixing coefficients of a GMM for its EM algorithm to effectively reduce to the k-means algorithm?
- ii. Explain how the "hard" assignment of k-means (each point belongs to exactly one cluster) contrasts with the "soft" assignment in GMMs.

3. Consider below Markov Decision Process (MDP) with four states:  $A$ ,  $B$ ,  $C$ , and  $D$ . From states  $A$ ,  $B$ , and  $C$ , the agent can choose from the actions: **LEFT**, **RIGHT**, **UP**, or **DOWN**, unless obstructed by a wall in that direction. From state  $D$ , the only available action is a special **EXIT** action, which grants the agent a terminal reward of  $x$ . All other actions (non-exit actions) yield a reward of 1.



(a) **(Deterministic actions)**

Assume all actions are deterministic, and the discount factor is  $\gamma = \frac{1}{2}$ . Express the value function  $V^*(s)$  for the following states in terms of  $x$ , given that the optimal value function satisfies:

$$\begin{array}{ll} V^*(D) = & V^*(A) = \\ V^*(C) = & V^*(B) = \end{array}$$

(b) **(Stochastic actions)**

Now suppose each non-exit action succeeds with probability  $\frac{1}{2}$ ; otherwise, the agent remains in the same state and receives a reward of 0. The **EXIT** action from state  $D$  is still deterministic and always succeeds. Let  $\gamma = \frac{1}{2}$  as before.

Find the value of  $x$  for which the agent is indifferent between two actions from state  $A$ : taking action DOWN to go to  $D$ , and taking action RIGHT to go to  $B$ . In other words, solve for  $x$  such that:

$$Q^*(A, \text{DOWN}) = Q^*(A, \text{RIGHT})$$

4. Consider a Gridworld scenario where an agent aims to estimate the value function of each state using TD Learning and Q-Learning.

	A	
B	C	D
	E	

Suppose we observe the following  $(s, a, s', R(s, a, s'))$  transitions and rewards (in order from left to right):

$$(B, \text{East}, C, 2), \quad (C, \text{South}, E, 4), \quad (C, \text{East}, A, 6), \quad (B, \text{East}, C, 2)$$

Assume the initial value of each state is 0, the discount factor  $\gamma = 1$ , and the learning rate  $\alpha = 0.5$ .

- What are the learned state values from TD learning after all four transitions?
- What are the learned Q-values from Q-learning after all four observations? Use the same  $\alpha = 0.5$  and  $\gamma = 1$ .